

# CENTRALLY NILPOTENT SKEW BRACES

(JOINT W. ERIC JESPERS, LEANDRO VENDRAMIN)

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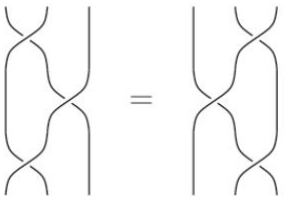
## THE YANG-BAXTER EQUATION: A PICTURE

### Definition

A set-theoretic solution to the Yang-Baxter equation is a tuple  $(X, r)$ , where  $X$  is a set and  $r : X \times X \rightarrow X \times X$  a function such that (on  $X^3$ )

$$(r \times \text{id}_X) (\text{id}_X \times r) (r \times \text{id}_X) = (\text{id}_X \times r) (r \times \text{id}_X) (\text{id}_X \times r).$$

For further reference, denote  $r(x, y) = (\lambda_x(y), \rho_y(x))$ .



## DEFINITIONS AND EXAMPLES

### Definition

A set-theoretic solution  $(X, r)$  is called

- ▶ left (resp. right) non-degenerate, if  $\lambda_x$  (resp.  $\rho_y$ ) is bijective,
- ▶ non-degenerate, if it is both left and right non-degenerate,
- ▶ involutive, if  $r^2 = \text{id}_{X \times X}$ ,

### Examples

- ▶ Twist solution:  $r(x, y) = (y, x)$ ,
- ▶ Lyubashenko, where  $f, g : X \rightarrow X$  are maps with  $fg = gf$ :  
 $r(x, y) = (f(y), g(x))$ .

## THE STRUCTURE MONOID AND GROUP

### Definition

Let  $(X, r)$  be a set-theoretic solution of the Yang-Baxter equation. Then the group

$$G(X, r) = \langle x \in X \mid xy = \lambda_x(y)\rho_y(x) \rangle,$$

is called the structure group of  $(X, r)$ .

## WHAT ARE SKEW LEFT BRACES

### Definition (Rump, CJO, GV)

Two groups  $(A, +)$  and  $(A, \circ)$  form a skew left brace  $(A, +, \circ)$ , if for any  $a, b, c \in A$ , it holds that

$$a \circ (b + c) = (a \circ b) - a + (a \circ c),$$

where  $-a$  denotes the inverse of  $a$  in  $(A, +)$ .

Moreover, if  $(A, +)$  is abelian, then  $(A, +, \circ)$  is a left brace

## EXAMPLES OF SKEW BRACES

### Example

1. Every group  $(G, +)$  has the skew left brace structure  $(G, +, +)$ , these are *trivial skew left braces*.
2. The dihedral group  $D_{2n} = \langle a, b \mid a^n = b^2 = 1, bab = a^{-1} \rangle$  has a left brace structure, where  $a^i b^j + a^k b^l = a^{i+k+jl} b^{j+l}$  with  $j, l \in \{0, 1\}$ .
3. Radical rings.

## CREATING SOLUTIONS ON SKEW BRACES (1)

### Definition (Rump, CJO, GV)

Let  $(B, +)$  and  $(B, \circ)$  be groups on the same set  $B$  such that for any  $a, b, c \in B$  it holds that

$$a \circ (b + c) = (a \circ b) - a + (a \circ c).$$

Then  $(B, +, \circ)$  is called a skew (left) brace

If  $(B, +)$  is abelian, one says that  $(B, +, \circ)$  is a left brace.

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Denote for  $a, b \in B$ , the map  $\lambda_a(b) = -a + a \circ b$ . Then,  $\lambda : (B, \circ) \rightarrow \text{Aut}(B, +) : a \mapsto \lambda_a$  is a well-defined group morphism.



## CREATING SOLUTIONS ON SKEW BRACES (2)

### Theorem

*Let  $(B, +, \circ)$  be a skew left brace. Denote for any  $a, b \in B$ , the map  $r_B(a, b) = (\lambda_a(b), \overline{\bar{a} + b}) \circ b$ . Then  $(B, r_B)$  is a bijective non-degenerate solution. Moreover, if  $(B, +)$  is abelian, then  $(B, r_B)$  is involutive.*

### Remark

*Let  $(X, r)$  be a bijective non-degenerate set-theoretic solution. Then,  $G(X, r)$  is a skew left brace and carries an associated solution as a skew brace.*

## THE \*-OPERATION IN SKEW LEFT BRACES

### Definition

Let  $(A, +, \circ)$  be a skew left brace. For any  $a, b \in A$ , denote

$$a * b = -a + a \circ b - b = \lambda_a(b) - b.$$

Denote  $X * Y$  for the additive subgroup generated by  $x * y$ , where  $x \in X, y \in Y$  and  $X, Y \subseteq A$ .

### Example

1. For  $(G, +, +)$ , one sees that  $a * b = 0$ . Actually a characterization.
2. For  $(D_{2n}, +, \cdot)$  one can see that  $(a^i b^j) * (a^k b^l) \in \langle a \rangle$ .

## SOLUTIONS LIKE LYUBASHENKO'S

### Definition (Retraction)

Let  $(X, r)$  be a finite bijective non-degenerate set-theoretic solution. Define the relation  $x \sim y$  on  $X$ , when  $\lambda_x = \lambda_y$  and  $\rho_x = \rho_y$ . Then, there exists a natural set-theoretic solution on  $X/\sim$  called the retraction  $\text{Ret}(X, r)$ .

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Denote for  $n \geq 2$ ,  $\text{Ret}^n(X, r) = \text{Ret}(\text{Ret}^{n-1}(X, r))$ . If there exists a positive integer  $n$  such that  $|\text{Ret}^n(X, r)| = 1$ , then  $(X, r)$  is called a multipermutation solution

## WHY ARE MULTIPERMUTATION SOLUTIONS INTERESTING

### Theorem (CJOBVAGI)

Let  $(X, r)$  be a finite involutive non-degenerate set-theoretic solution. The following statements are equivalent,

- ▶ the solution  $(X, r)$  is a multipermutation solution,
- ▶ the group  $G(X, r)$  is left orderable,
- ▶ the group  $G(X, r)$  is diffuse,
- ▶ the group  $G(X, r)$  is poly- $\mathbb{Z}$ .

Breaks down for non-involutive solutions, as  $G(X, r)$  has torsion in that case!

## ALL MULTIPERMUTATION SOLUTIONS

### Proposition

*Let  $(X, r)$  be a multipermutation solution, then the skew brace  $G(X, r)$  is of nilpotent type.*

So we focus attention on so-called skew braces  $(B, +, \circ)$  of **nilpotent type**, i.e.  $(B, +)$  is a nilpotent group.

## NON-ASSOCIATIVE, SO SIDES MATTER

### Left Nilpotent

- ▶  $B^{n+1} = B * B^n$  left ideals
- ▶  $|B^k| = 1$ , then left nilpotent
- ▶ Nilpotent type:  
( $B, \circ$ ) nilpotent
- ▶ Example:  $(C_{2^n}, D_{2^n})$

### Right nilpotent

- ▶  $B^{(n+1)} = B^{(n)} * B$  ideals
- ▶  $|B^{(k)}| = 1$ , then right nilpotent
- ▶ Nilpotent type:  
( $B, r_B$ ) multipermutation
- ▶ Example:  $(C_{2n}, D_{2n})$

## MEASURING MULTIPERMUTATION

### Definition

A skew brace  $(B, +, \circ)$  is said to be multipermutation, if  $(B, r_B)$  is multipermutation.

Equivalently:

- ▶  $B$  is right nilpotent of nilpotent type,
- ▶ The chain  $\text{Soc}^n(B)$  ends in  $B$ .

Here,  $\text{Soc}^{n+1}(B)$  is the pullback in  $B$  of  $\text{Soc}(B/\text{Soc}^n(B))$  with

$$\text{Soc}(A) = \ker \lambda \cap Z(B, +).$$



## CENTRAL NILPOTENCY

### Definition

Let  $B$  be a skew brace. Denote  $Ann(B) = Soc(B) \cap Z(B, \circ)$ .

Equivalently,

$$Ann(B) = \{x \in Z(B, +) \mid \lambda_x = id_B, \lambda_y(x) = x \text{ for all } y \in B\}.$$

### Definition

Let  $B$  be a skew brace. One says that  $B$  is centrally nilpotent, if the chain  $Ann^n(B)$  ends in  $B$ , where  $Ann^{k+1}(B)$  is pullback of  $Ann(B/Ann^k(B))$ .

## DESCENDING SERIES

We have an ascending ideal series, what about descending?

$$\Gamma_{n+1}(B, I) = \langle B * \Gamma_n(B, I), \Gamma_n(B, I) * B, [\Gamma_n(B, I), B]_+ \rangle$$

is an ideal in  $B$ , if  $I$  is an ideal.

### Proposition (Bonatto, Jedlicka)

*Let  $B$  be a skew brace. Then,  $B$  is centrally nilpotent, if for some positive integer  $n$  we have  $\Gamma_n(B, B) = 1$ .*

## STRONGLY NILPOTENT

$$B^{[n]} = \langle B^{[i]} * B^{[n-i]} \mid 1 \leq i \leq n \rangle.$$

### Proposition (Smoktunowicz)

*Let  $B$  be a skew brace. Then,  $B$  is strongly nilpotent if and only if  $B$  is left and right nilpotent and  $(B, \circ)$  is nilpotent.*

What if we account for additive commutator?

$$\Gamma_{[n]}(B) = \langle \Gamma_{[i]}(B) * \Gamma_{[n-i]}(B), [\Gamma_{[i]}(B), \Gamma_{[n-i]}(B)]_+ \rangle$$

### Proposition (Jespers, AVA, Vendramin)

*Let  $B$  be a skew brace of nilpotent type. If  $B$  is centrally nilpotent, then  $B$  is strongly centrally nilpotent. Moreover,  $B$  is strongly nilpotent.*

## NILPOTENCY CLASS

Both the chains  $\Gamma_n(B)$  and  $\Gamma_{[n]}(B)$  allow to define a notion of nilpotency class of  $B$ .

### Problem

- ▶ *Can we relate the above nilpotency classes?*
- ▶ *Are there bounds using the additive/multiplicative nilpotency class?*

## FINITELY GENERATED

### Proposition (Jespers, AVA, Vendramin)

Let  $B$  be a centrally nilpotent skew brace with ACC on sub skew braces. TFAE

- ▶  $B$  is finitely generated as a brace,
- ▶  $(B, +)$  is finitely generated as a group,
- ▶  $(B, \circ)$  is finitely generated as a group.

Vice versa, every finitely generated Centrally nilpotent skew brace has ACC on sub skew braces.

## TORSION

What is torsion in a skew brace?

**Proposition (Jespers, AVA, Vendramin)**

*Let  $B$  be a centrally nilpotent skew brace. Then  $T_+(B) = T_0(B)$ , which is an ideal of  $B$ . Finite, if  $B$  is finitely generated.*

**Proposition (Jespers, AVA, Vendramin)**

*Let  $B$  be a centrally nilpotent skew brace. If  $T_+(B) = 0$ . Then,  $a^n = b^n$  or  $na = nb$  implies  $a = b$ .*

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